Minutes for Team HEV Weekly Meeting with Professor Schafer, 03/01/2010:
Action Items—Closed
A. MOSFET Circuitry
a. All 4 sensor circuits complete
b. Starter circuit complete
c. On/off circuit complete
d. Glow plug circuit complete
e. Monday: acquiring sensors to do final tests with microcontroller
All fine, current op/amps are fine but get different ones for demos
B. Microcontroller Programming
C. GPS
a. Inventek Systems:
☐ Confirmed it will do latitude/longitude and altitude
1. Rep said not as accurate in altitude measurements (bu
that's the case for all GPS, it will be accurate enough for
our uses)
☐ Functional Specifications:
1. Serial communication: support transmit/receive on
two ports, each implemented by a UART
a. Supports two protocols (SIRF Binary and NMEA
0183)
Will affect board layout
Serial port so that is good
SMA plug for antenna but have to maintain 50 ohms on that line
D. Charging Circuitry: completed
a. Testing
- 80 amps through ultracapacitors with 50 V across ~ 4kW
- Motors of wheels run off of 4 kW that is good
- Modified 2:1 transformer to a 3:2 transformer
- Entire system is ready to be loaded onto the truck
Action Items—Open
A. Low Level Design
a. Demo: Schedule for Wednesday or Thursday of this week
☐ Will complete testing today and tomorrow
b. Document
☐ Final Updates will be completed by demo
B. Ultracapacitor Boxes
a. Will check with Dr. Bauer's grad student
Talk to Bauer and other partners
C. GPS
a. Order
b. Begin figuring out interface
D. 70 A Fuse
Don't need anymore because there is already one on the box

Other Notes:

Current microcontroller is hard to soder, small spacing on pins Don't need two serial ports, only 1 Need an SPI port for the S/D card Look at spec sheet carefully only have one shot

Issues:

Running out of gas
Button reset
Can I overdrain the Ultracaps
Charge dead Ultracaps?
What are the controls of the driver to this board