Rocketry Team Payload

Brittany Cahill Chris Susco Javier Rivera González MaryKate Drennan Patrick Cremin



Introduction

Design

A planetary landing system.

Launch

The system will be launched in a rocket.

Landing

The system must land in an upright configuration.



Function

It will take a 360 degree panoramic photo.

Transmission

It will transmit this photo wirelessly.

Name

Landon Planette

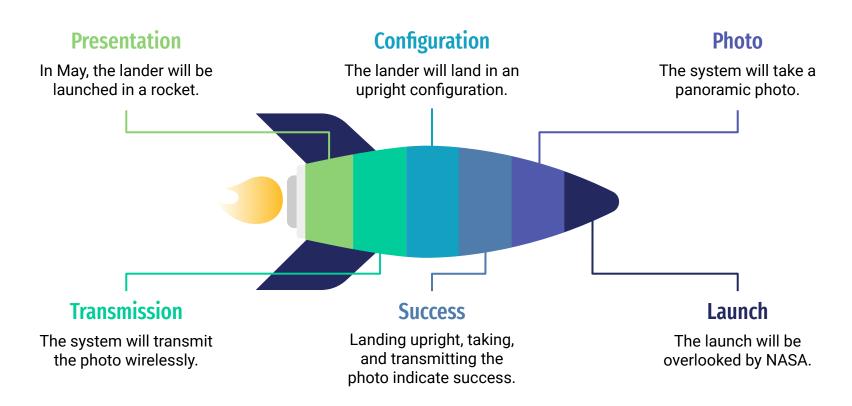
Problem Description



Proposed Solution



Demonstrated Features



Available Technologies

Microcontroller

The Raspberry Pi Zero has been selected as the microcontroller.

Cameras

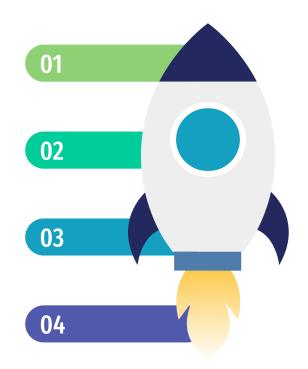
Four cameras and associated hardware will be needed to take the panoramic photo.

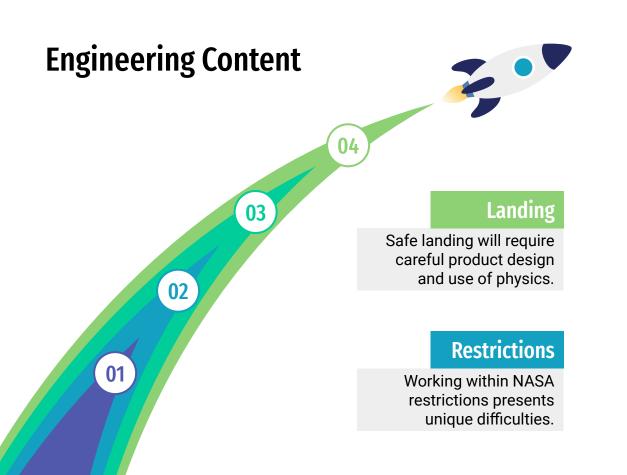
Wireless Interface

An RF transceiver will be necessary to transmit the photo.

Others

Absolute orientation sensor, battery, boost converter, antenna.





Transmission

Working with the Pi Zero will require EE and coding knowledge.

Teamwork

Work closely with other subsystems and keep the project compact.

Conclusions

Working with Rocketry Team will provide a highly technical experience with exciting EE applications.



Challenges

The team must tackle several unique obstacles.

Teamwork

Working well in a smaller system team and larger rocket team is crucial to success.

Result

The project must succeed in landing, photographing, and transmitting.

Limitations

Working within the confines of budget and space will provide realistic project experience.